Turbomachinery & Turbulence. Lecture 4: Design and analysis of an axial-flow compression stage.

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Moment of momentum

- Fluid enters at a flow rate ṁ at r₁ with tangential velocity C_{θ1}.
- It leaves the control volume at r₂ with tangential velocity C_{θ2}.
- Moment of momentum, steady version, along a streamline:

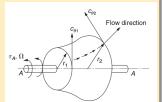
$$\tau_{\mathsf{a}} = \dot{m} \left(r_2 C_{\theta 2} - r_1 C_{\theta 1} \right)$$

• Power:

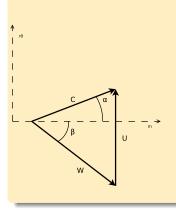
$$\tau_{\mathsf{a}}\omega = \dot{m}\left(U_2 C_{\theta 2} - U_1 C_{\theta 1}\right)$$

• Link to energy exchange (steady process, adiabatic):

$$\Delta h_0 = \Delta \left(U C_\theta \right)$$



Rothalpy



• Along a streamline, the quantity called *rothalpy* is constant:

$$I = h_0 - UC_\theta = cte$$

• Using the velocity triangle:

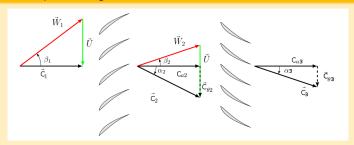
$$I = h + \frac{W^2}{2} - \frac{U^2}{2} = \text{cte}$$

• Different contributions:

$$\Delta h_0 = \Delta \left(U W_\theta \right) + \Delta \left(U^2 \right)$$

• Aerodynamic forces work + Coriolis forces $(2\vec{\omega} \times \vec{W})$ work.

Axial-flow compression stage

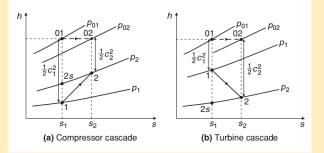


• Axial-flow stage: U = cte along a streamline. If one assumes $C_m = \text{cte}$:

$$\begin{array}{rcl} \Delta h_0 & = & U \left(W_{\theta 2} - W_{\theta 1} \right) \\ & = & U C_m \left(\tan \beta_2 - \tan \beta_1 \right) \end{array}$$

- Watch out: $\beta < 0$. For a compression, $|W_{\theta 2}| < |W_{\theta 1}| \Rightarrow h_2 > h_1$.
- Stator: $h_0 = \text{cte}$ but $|C_3| < |C_2| \Rightarrow h_3 > h_2$.
- Conversion of kinetic energy to pressure (and degradation to internal energy).
- The relative flow is decelerated in the rotor. The absolute flow is decelerated in the stator. Diffusion (adverse pressure gradient) limits deflection to 40°.

Mechanical energy loss



Mollier diagram for a steady blade cascade $h_{02} = h_{01}$.

Losses are related to Δp_0 :

$$\int T_0 ds_0 = -\int \frac{dp_0}{\rho_0}$$
$$\Delta f \simeq \frac{p_{02} - p_{01}}{\rho_{01}}$$

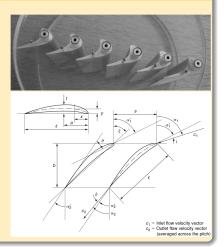
Losses with respect to isentropic are related to kinetic energy:

Is. Loss
$$= \frac{1}{2} \left(C_{2s}^2 - C_2^2 \right)$$

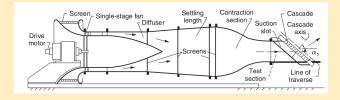
Blade cascade

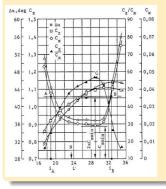
$$\Delta h_0 = UC_m (\tan \beta_2 - \tan \beta_1)$$

- Work depends on flow deflection $\Delta\beta$.
- Two-dimensional profile:
 - *I*: chord length
 - t: thickness of the profile
 - θ : camber angle.
 - α'_{1,2}: blade inlet (outlet) angle
- Two-dimensional cascade:
 - ξ: stagger angle
 - $\sigma = l/s$: solidity
 - α_{1,2}: inlet (outlet) flow angle
 - $i = \alpha_1 \alpha'_1$: incidence angle
 - $\delta = \alpha_2 \alpha'_2$: deviation
 - $\epsilon = \alpha_2 \alpha_1$: deflection
 - $aoa = \alpha_1 \xi$: angle of attack



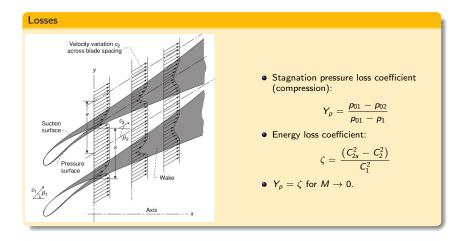
Cascade characteristics





- Blade profiles: a certain thickness distribution (NACA65, British C series,...)
- Cascade characteristics: for given profiles, stagger angle and solidity,
- as a function of α₁, M₁, Re₁:
 - Exit flow angle α₂
 - stagnation pressure loss coefficient Y_P

The results are also presented as ϵ as a function of aoa, as lift and drag coefficient or as energy loss coefficient $\zeta.$



Actual 3D flows

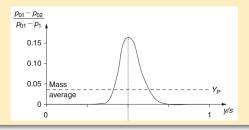
Cascade parameters measurements

- ullet Measurements are performed $\simeq 1 {\it I}$ upstream and downstream of the cascade.
- Mass-averaged quantities along one (two) pitch are given:

$$\dot{m} = \int_{0}^{s} \rho C_{x} dy$$

$$\tan \alpha_{2} = \frac{\int_{0}^{s} \rho C_{x} C_{y} dy}{\int_{0}^{s} \rho C_{x}^{2} dy}$$

$$Y_{p} = \frac{\int_{0}^{s} \left\{ (p_{01} - p_{02}) / (p_{01} - p_{1}) \right\} \rho C_{x} dy}{\int_{0}^{s} \rho C_{x} dy}$$



Application to rotors and stators

- Cascades are stationary \Rightarrow straightforward for stator blades.
- For rotors, replace:
 - α by β .
 - \vec{C} by \vec{W} .
 - h₀ by h_{0,rel}.

Losses and efficiency: incompressible flow compression stage

- Incompressible flow, temperature change is negligible, $\rho = cte$.
- Upstream rotor: 1, between rotor and stator: 2, downstream stator: 3.
- Actual work:

$$\Delta W = h_{03} - h_{01}$$

• Minimum work required to attain same final stagnation pressure:

$$\Delta W_{min} = h_{03ss} - h_{01}$$

• Along $p = p_{03}$, second law gives:

$$\Delta W_{min} = \Delta W - T \Delta s_{stage}$$
 $\eta_{tt} = rac{\Delta W_{min}}{\Delta W} = 1 - rac{T \Delta s_{stage}}{h_{03} - h_{01}}$

Losses and efficiency: incompressible flow compression stage

• Accross the rotor, $h_{0,rel} = \text{cte}$:

$$T\Delta s_{rotor} = rac{\Delta p_{0,rel}}{
ho} = rac{1}{2} W_1^2 Y_{
ho,rotor}$$

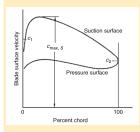
• Accross the stator,
$$h_0 = \text{cte}$$
:

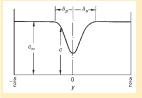
$$T\Delta s_{stator} = rac{\Delta p_0}{
ho} = rac{1}{2}C_2^2Y_{
ho,stator}$$

• Thus:

$$\eta_{tt} = 1 - \frac{\frac{1}{2} \left(W_1^2 Y_{p,rotor} + C_2^2 Y_{p,stator} \right)}{h_{03} - h_{01}}$$

Losses and efficiency: incompressible flow compression stage



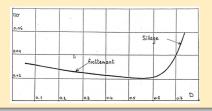


- Adverse pressure gradient: boundary layer growth (and detachment).
- Wake momentum thickness θ_2 correlated to diffusion on suction side.

$$\theta_2 = \int_{-s/2}^{s/2} \left(\frac{C}{C_{\infty}}\right) \left(1 - \frac{C}{C_{\infty}}\right) dy$$

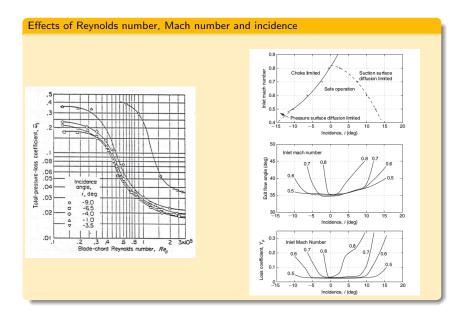
• Diffusion factor linked to solidity:

$$DF = \left(1 - rac{C_2}{C_1}
ight) + \left(rac{|C_{ heta_2} - C_{ heta_1}|}{2\sigma C_1}
ight)$$

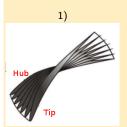


One dimensional Theory 0000 Blade loading, boundary layers and losses Design methodology for an axial-flow stage

Actual 3D flows



Radial dependence & spanwise velocities



 $U = r\omega \Rightarrow$ stagger angles depend on r.

2)

• Bernoulli theorem accros streamlines:

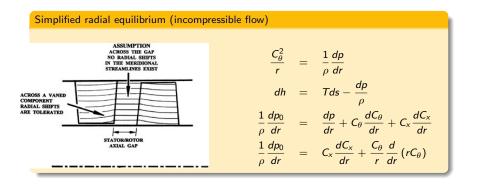
C_{θ}^2	=	$\frac{1}{2} \frac{\partial p}{\partial p}$
r		ρðr

- For hub-to-tip ratio $r_h/r_t \lesssim 0.8$,
- temporary imbalance between centrifugal forces and radial pressure gradients.
- streamlines bend radially until sufficient radial transport to recover equilibrium.

3)

Simplified radial equilibrium hypothesis:

- Permanent flow;
- Outside blade rows;
- Cylindrical streamtubes;
- Viscous stress neglected:



Radial repartition of the work: vortex law

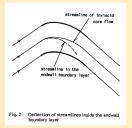
- Free vortex: $rC_{\theta} = cte$
- Constant vortex: $C_{\theta} = cte$
- Forced vortex: $C_{\theta} = \operatorname{cte} \cdot r$
- Constant absolute angle: $C_{\theta}/C_z = cte$
- General vortex: $C_{\theta} = k_1 r^n + k_2 \frac{1}{r}$

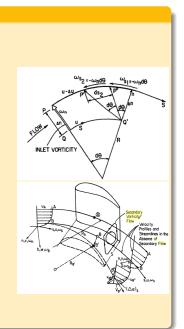
Actual 3D flows

"Passage vortex": mechanisms

Flows induced in transverse (S3) surfaces, by creation of meridional vorticity.

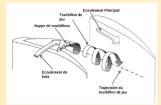
- Vorticity tends to conserve.
- Boundary layers on hub and casing are vortical regions (vorticity ω_p).
- Deflection ϵ .
- \Rightarrow creation of a pair of passage vortices (ω_s) .
- $\omega_s \simeq 2\epsilon \omega_p$.
- Other explanation based on blade-to-blade pressure gradient and streamline curvature.



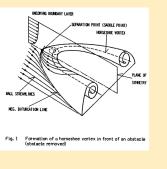


Other effects

 Horse-Shoe vortex: induced by boundary layer impinging on leading edge.



• Blade boundary layers and wakes: low momentum fluid is centrifuged (radial secondary flow).



• Tip leakage vortex: induced by flow instability in the radial gap between blade and casing.

Secondary flows, a misleading term

- These mechanisms exist, but they all non-linearly interact:
- Extremely difficult to identify them.

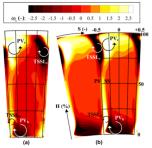


Fig. 5 Measured (5hp) (a) and predicted (b) streamwise vorticity ω_s at rotor inlet in the absolute frame of reference

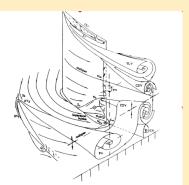
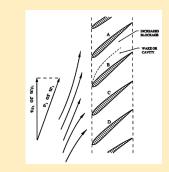


Figure I. Schematic of secondary flow structure in a compressor cascade with tip clearance, Kang [6]: PV – Passage vortex; HV – Horseshoe vortex; TLV – Tip leakage vortex; TSV – Tip secondary vortex; SV – Secondary vortex; CSV – Concentrated shot vortex; CV – Corner vortex

Stall, Stage stall and surge



Rotating stall: frequency of the order of the rotating frequency. Surge: system instability, slow time scales.

